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Nimmakayala et al.

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(54) **SUBSTRATE SUPPORT SYSTEM**

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(51) **Int. Cl.**
G03B 27/58 (2006.01)
G03B 27/62 (2006.01)

(52) **U.S. Cl.** **355/72; 355/75**

(58) **Field of Classification Search** **355/72, 355/75, 77; 269/266; 438/5**

See application file for complete search history.

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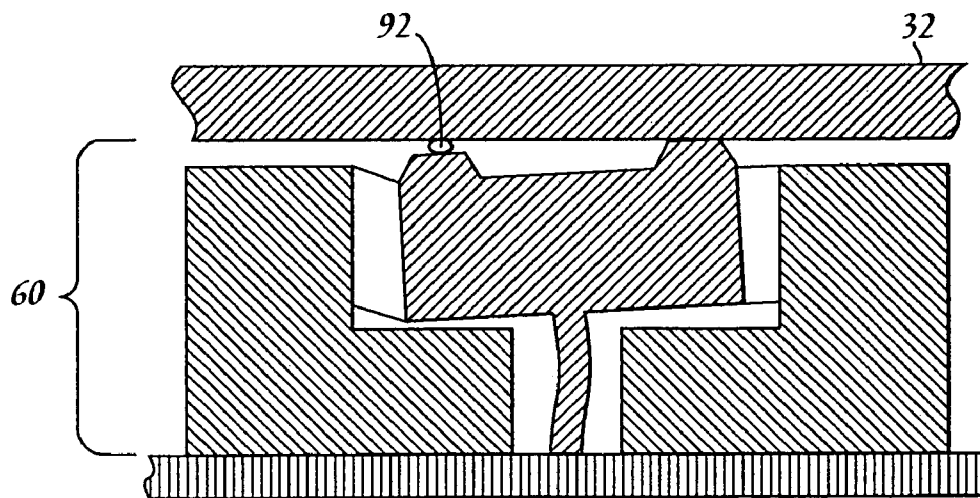
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(57) **ABSTRACT**

The present invention includes a substrate support system that features a chuck body having a body surface with a pin extending therefrom having a contact surface lying in a plane, with the pin being movably coupled to the chuck body to move with respect to the plane. As a result the substrate support system attenuates if not avoids generating non-planarity in a substrate that results from a presence of particulate contaminants. This is achieved by fabricating the pin to be compliant, allowing the same to move to accommodate the presence of the particle while maintaining sufficient planarity in the substrate.

24 Claims, 10 Drawing Sheets



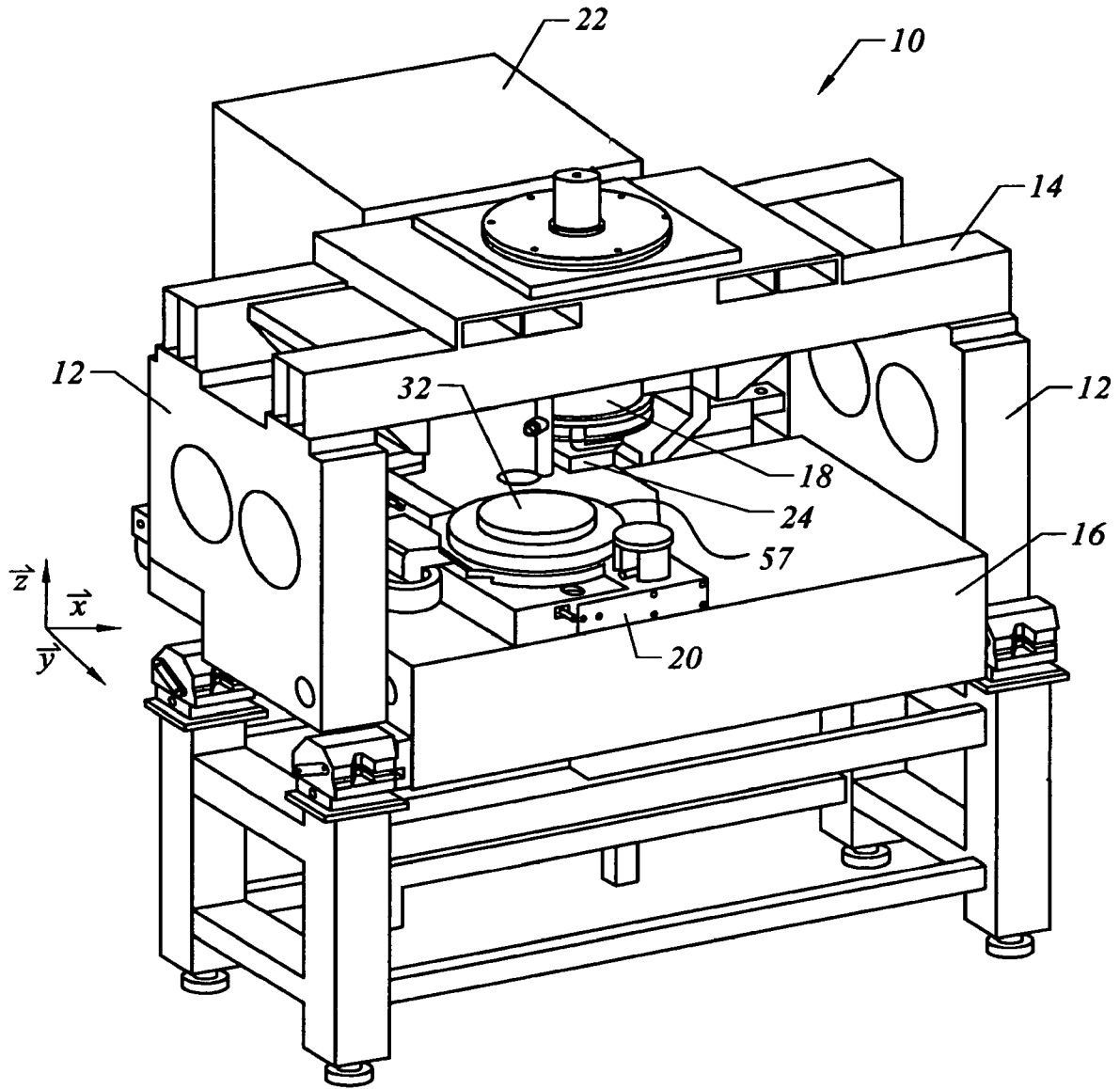


FIG. 1

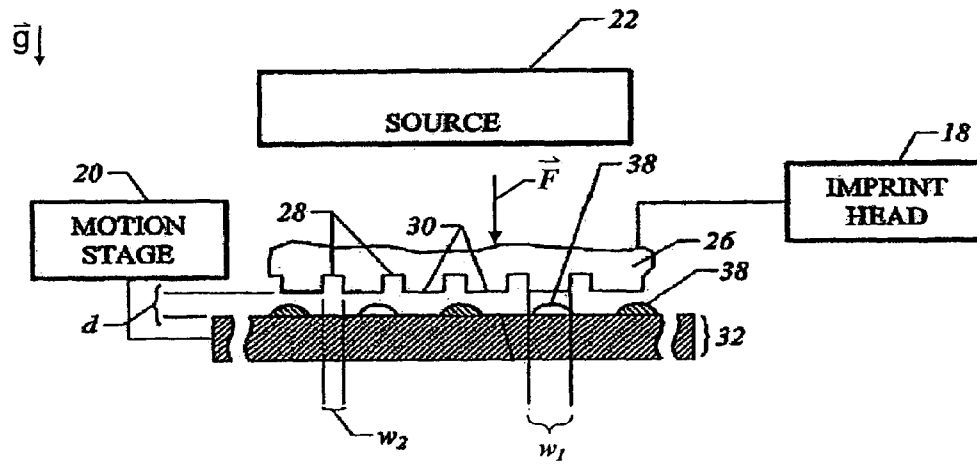


FIG. 2

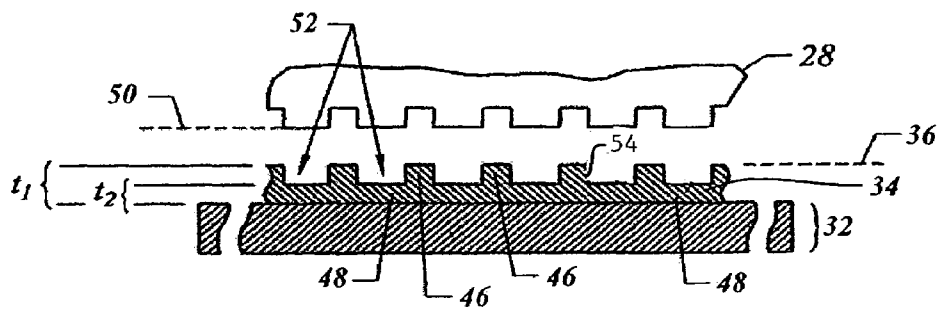


FIG. 3

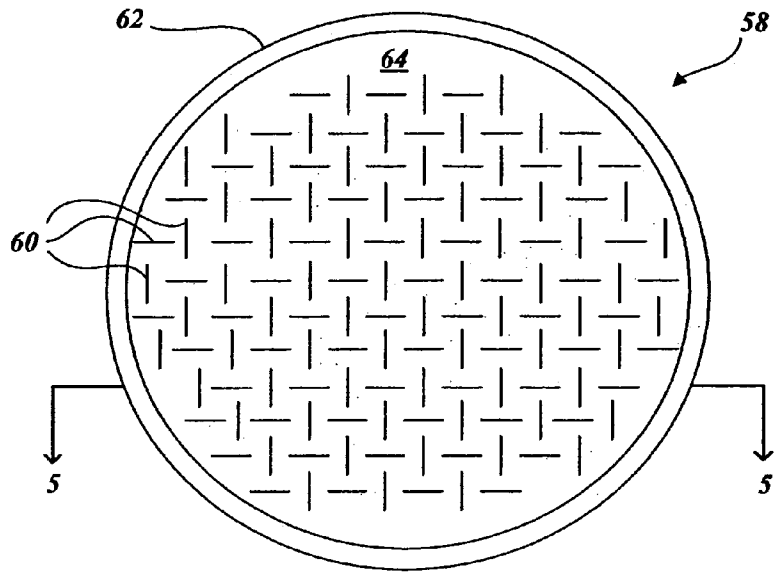


FIG. 4

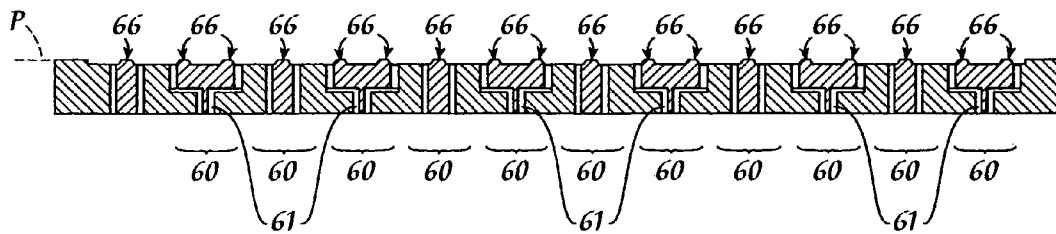


FIG. 5

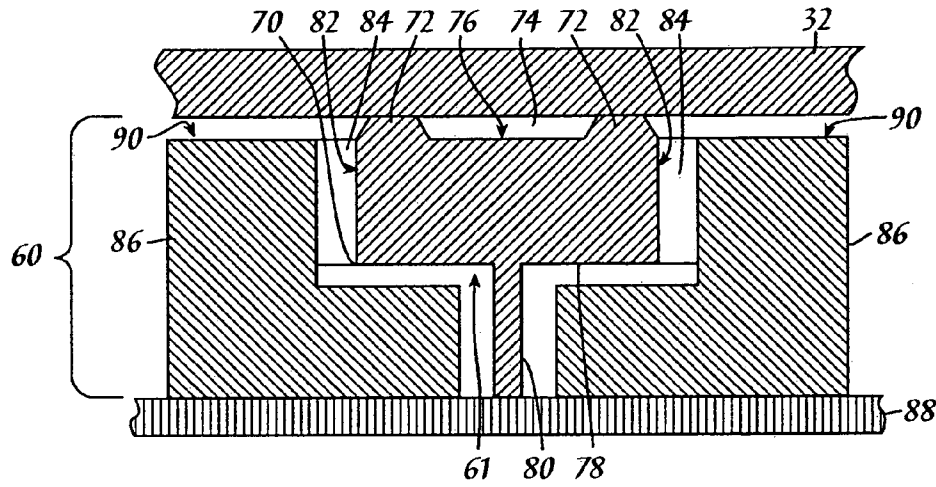


FIG. 6

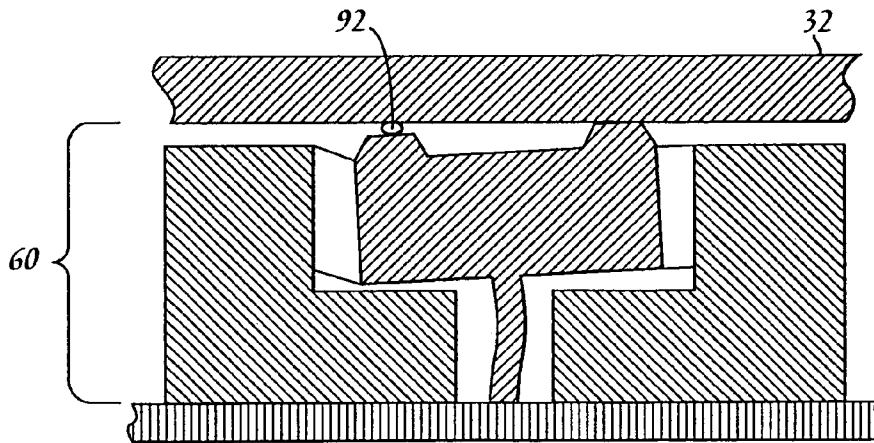


FIG. 7

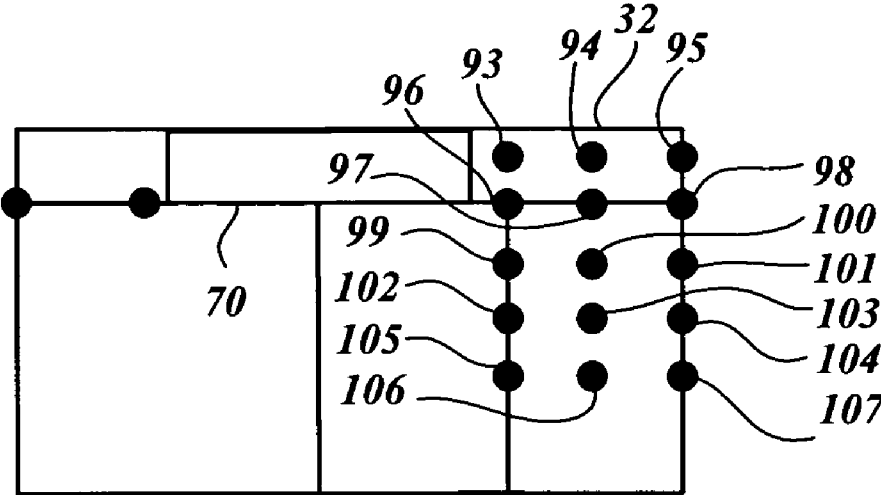


FIG. 8

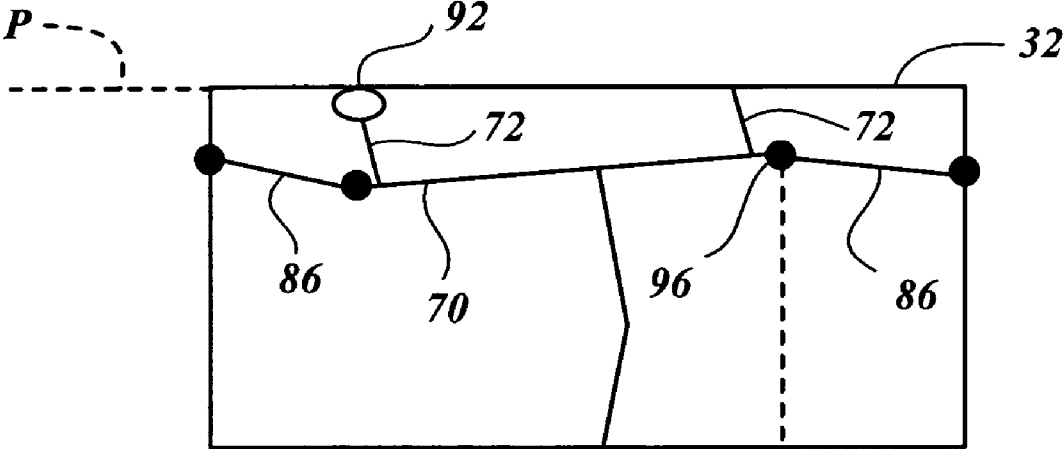


FIG. 9

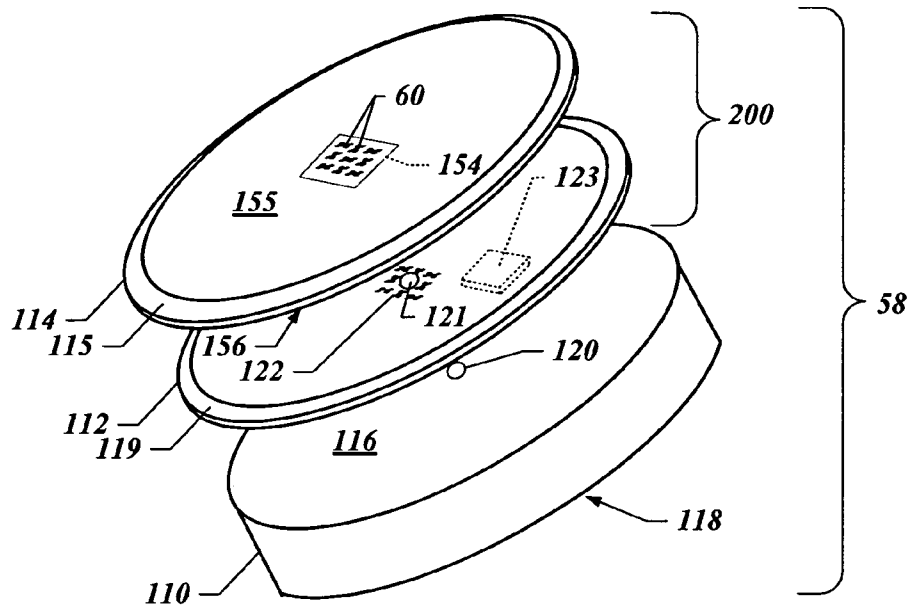


FIG. 10

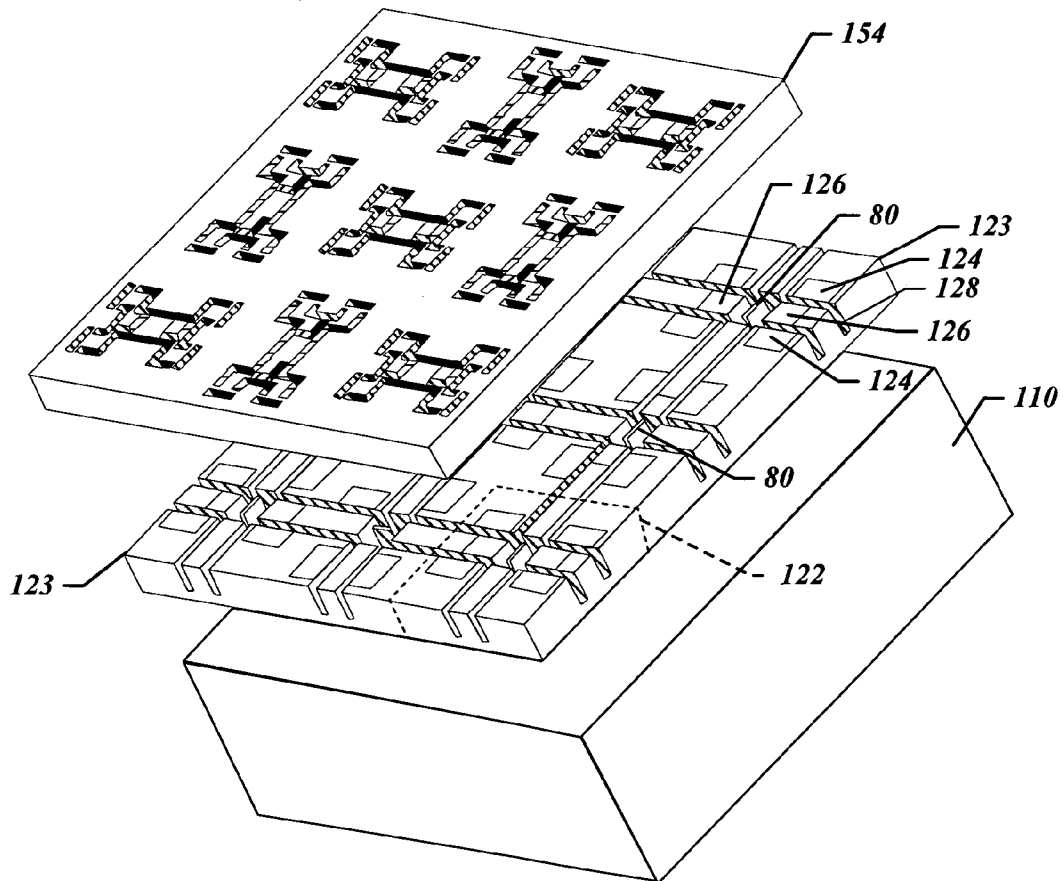


FIG. 11

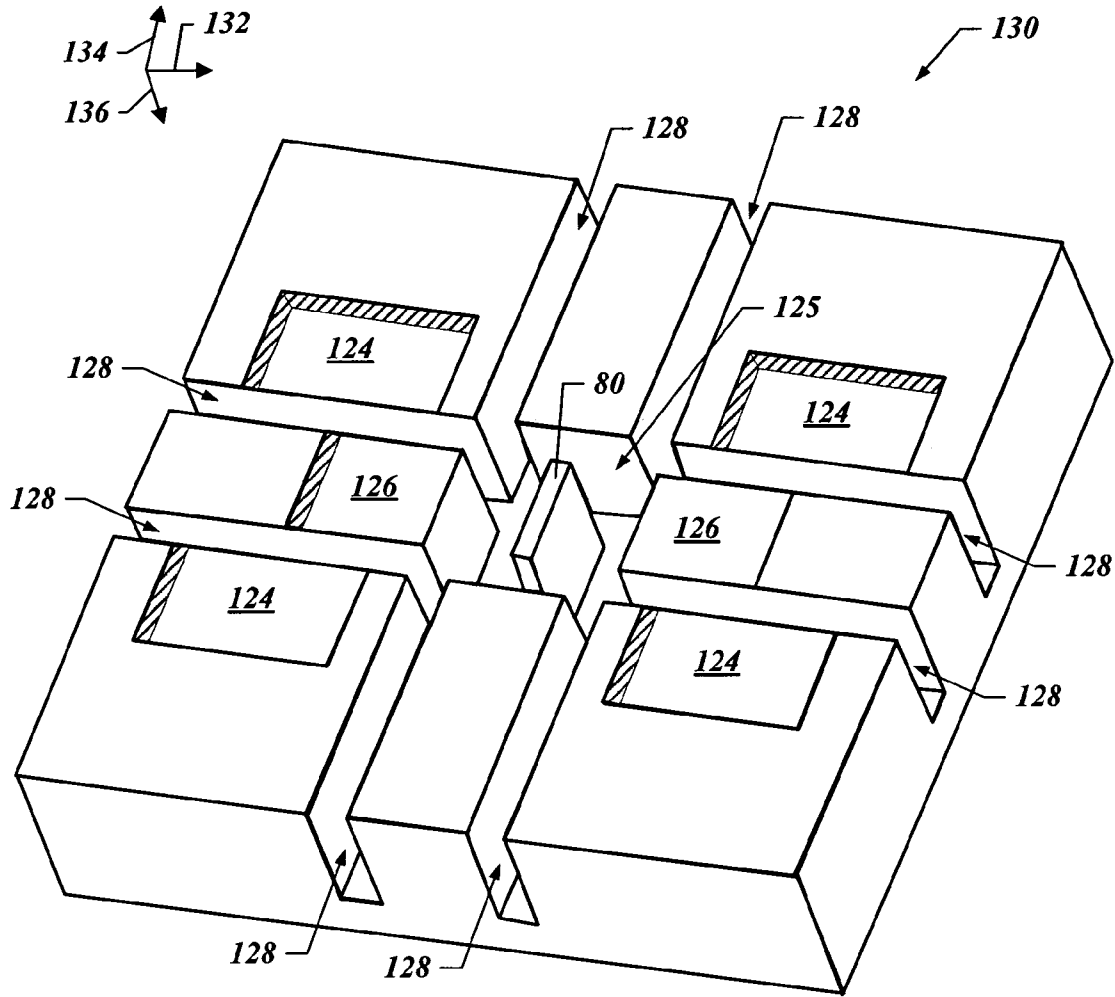


FIG. 12

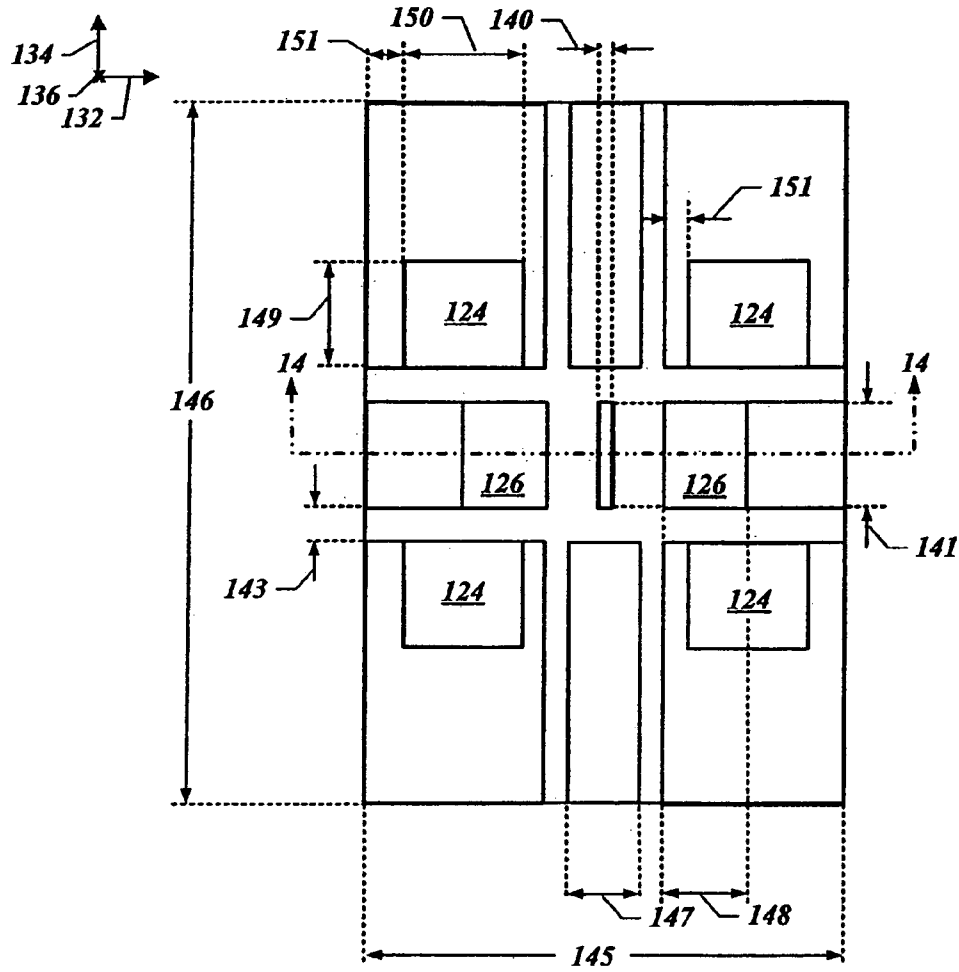


FIG. 13

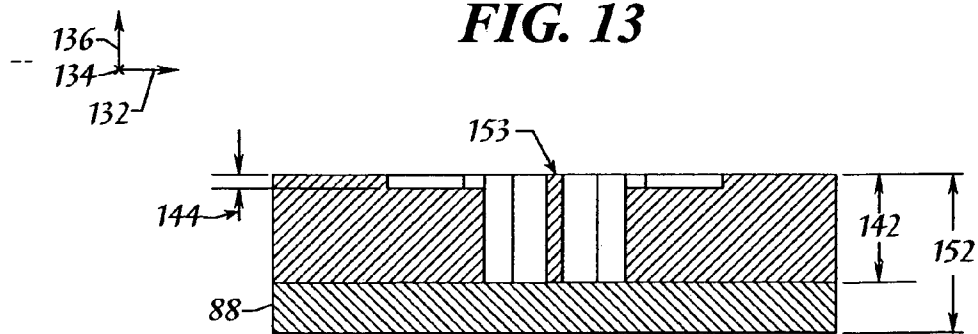


FIG. 14

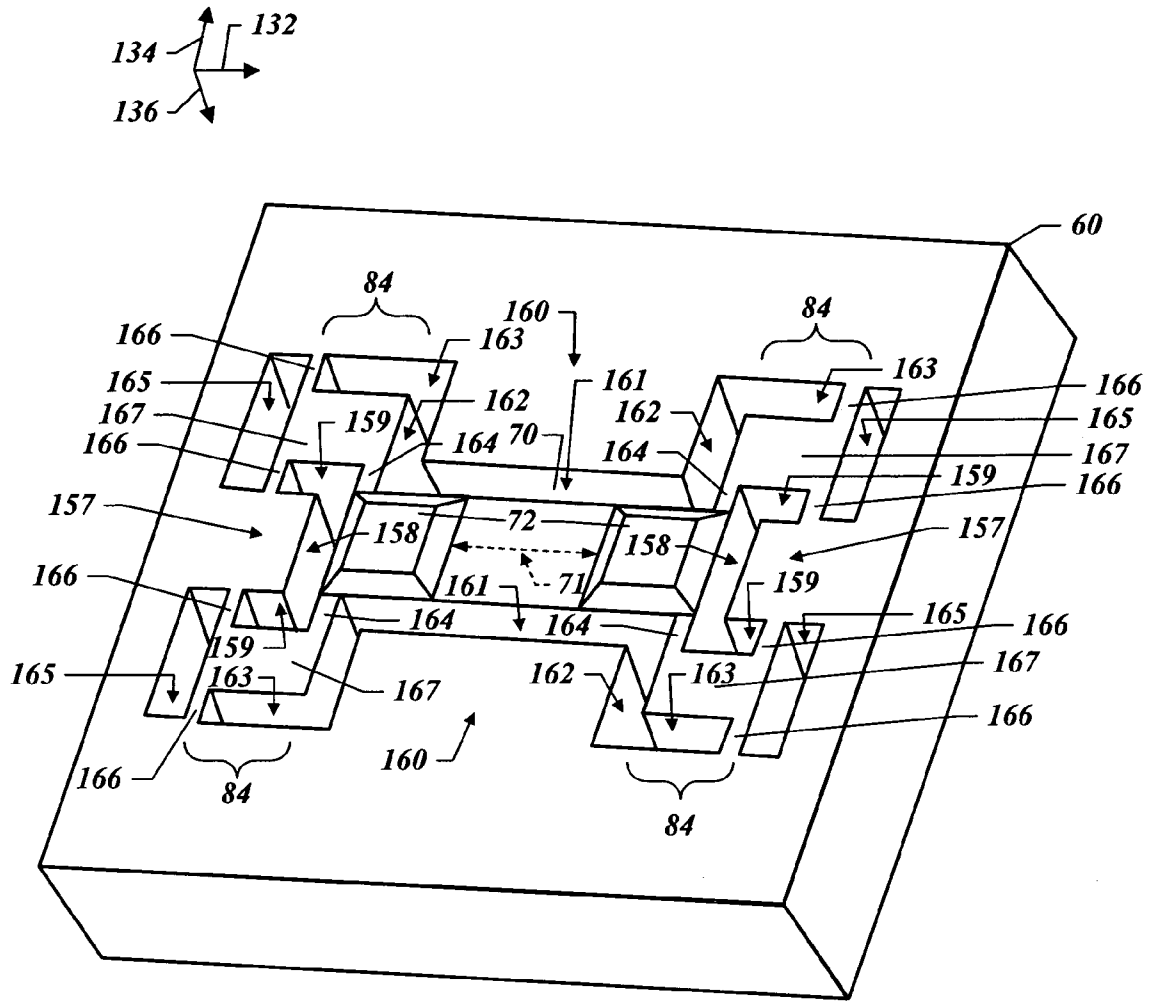


FIG. 15

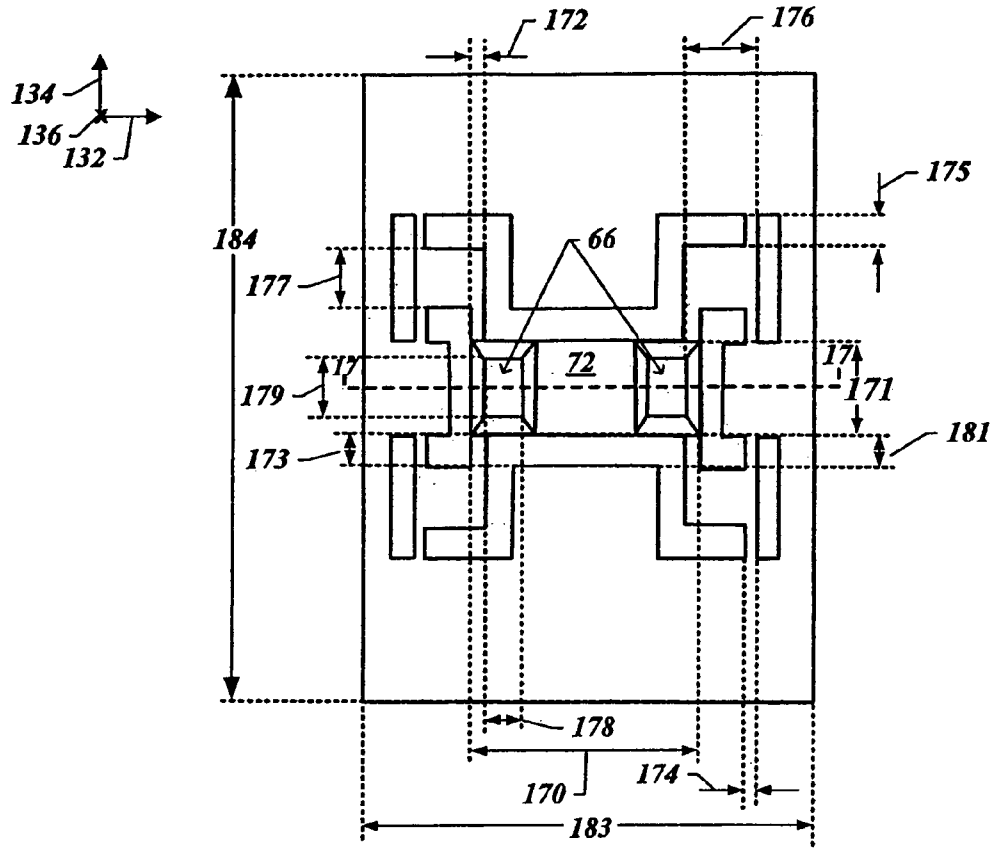


FIG. 16

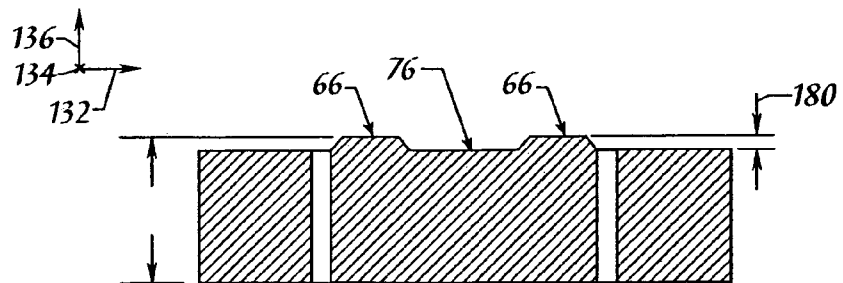


FIG. 17

SUBSTRATE SUPPORT SYSTEM**CROSS-REFERENCE TO RELATED APPLICATIONS**

The present application claims priority to U.S. Provisional patent application No. 60/575,442 entitled A CHUCKING SYSTEM AND METHOD, filed May 28, 2004 and having Pawan K. Nimmakayala and Sidlgata V. Sreenivasan listed as inventors and is a divisional patent application of U.S. patent application having Ser. No. 11/136,886 filed herewith and entitled SUBSTRATE SUPPORT METHOD listing Pawan K. Nimmakayala and Sidlgata V. Sreenivasan as inventors.

BACKGROUND OF THE INVENTION

The field of invention relates generally to support for substrates. More particularly, the present invention is directed to a chuck suited for use in imprint lithography.

Micro-fabrication involves the fabrication of very small structures, e.g., having features on the order of micro-meters or smaller. One area in which micro-fabrication has had a sizeable impact is in the processing of integrated circuits. As the semiconductor processing industry continues to strive for larger production yields while increasing the circuits per unit area formed on a substrate, micro-fabrication becomes increasingly important. Micro-fabrication provides greater process control while allowing increased reduction of the minimum feature dimension of the structures formed. Other areas of development in which micro-fabrication has been employed include biotechnology, optical technology, mechanical systems and the like. Many of the micro-fabrication techniques involve various processes, including deposition, such as chemical vapor deposition, physical vapor deposition, atomic layer deposition and the like, as well as wet and/or dry etching techniques to pattern substrates.

In addition to the standard micro-fabrication techniques, there exists a relatively new and efficient patterning technique referred to as imprint lithography. An exemplary imprint lithography is described in detail in numerous publications, such as U.S. Pat. No. 6,873,087 entitled HIGH PRECISION ORIENTATION ALIGNMENT AND GAP CONTROL STAGES FOR IMPRINT LITHOGRAPHY PROCESSES; U.S. Pat. No. 6,842,226, entitled IMPRINT LITHOGRAPHY TEMPLATE COMPRISING ALIGNMENT MARKS; U.S. Pat. No. 6,696,220 entitled TEMPLATE FOR ROOM TEMPERATURE, LOW PRESSURE MICRO-AND NANO-IMPRINT LITHOGRAPHY; and U.S. Pat. No. 6,719,915 entitled STEP AND FLASH IMPRINT LITHOGRAPHY, all of which are assigned to the assignee of the present invention. The fundamental imprint lithography technique as shown in each of the aforementioned published patent applications includes formatting a relief pattern in a polymerizable layer and transferring the relief pattern into an underlying substrate to form a relief image in the substrate. To that end, a template is employed spaced-apart from the substrate with a formable liquid present between the template and the substrate. The liquid is solidified forming a solidified layer that has a pattern recorded therein that is conforming to a shape of the surface of the template in contact with the liquid. The substrate and the solidified layer are then subjected to processes to transfer into the substrate a relief image that corresponds to the pattern in the solidified layer.

As a result of the aforementioned micro-fabrication techniques, the demand to ensure the flatness/planarity of sub-

strates being processed/patterned has increased, because of the decreasing size of the features being formed. There are a number of factors affecting substrate planarity, many of which can be corrected by conventional substrate chucks.

However, the presence of backside particles, particles that contact a surface of a substrate opposite to the surface being patterned, are problematic. For example, particles may become lodged between the substrate and the chuck, referred to as backside particles, which may cause out-of-plane distortion of the substrate resulting in distortions in the pattern generated on the substrate. Out-of-plane distortions may be characterized as possessing two parameters: 1) distortion height; and 2) gap radius. The distortion height is defined as the maximum out-of-plane deviation produced in the substrate by the backside particle. Gap radius is defined as a measure of the length of a region of the substrate spaced-apart from the chuck, measured between the particle and a point of the substrate closest to the particle at which the substrate contacts the chuck. It can be realized that the area of a substrate that undergoes distortion due to the presence of particulate contaminants is much greater than the size of the particulates.

Prior art attempts to overcome particulate contaminants include pin type and groove type chucks. These chucking systems attempt to avoid the drawbacks associated with backside particles by minimizing the contact area between the substrate and the chuck. However, these chucking systems only reduce the probability of particles being lodged between the chuck and the substrate, but do not avoid or attenuate the non-planarity should a particle get lodged between a chuck and a substrate.

There is a need, therefore, to provide improved support systems for substrates.

SUMMARY OF THE INVENTION

The present invention includes a substrate support system that features a chuck body having a body surface with a pin extending therefrom having a contact surface lying in a plane, with the pin being movably coupled to the chuck body to move with respect to the plane. As a result, the substrate support system attenuates, if not avoids, generating non-planarity in a substrate that results from a presence of particulate contaminants. This is achieved by fabricating the pin to be compliant, allowing the same to move to accommodate the presence of the particle while maintaining sufficient planarity in the substrate. These and other embodiments are discussed more fully below.

BRIEF DESCRIPTION OF THE DRAWINGS

FIG. 1 is a perspective view of a lithographic system in accordance with the present invention;

FIG. 2 is a simplified elevation view of a lithographic system, shown in FIG. 1, employed to create a patterned imprinting layer in accordance with the present invention;

FIG. 3 is a simplified cross-sectional view of a mold and substrate, shown in FIG. 2, after solidification of an imprinting layer on the substrate;

FIG. 4 is a top-down view of a chuck body employed in the chucking system, shown in FIG. 1, in accordance with one embodiment of the present invention;

FIG. 5 is a cross-sectional view of the chuck body, shown in FIG. 4, taken along lines 5—5;

FIG. 6 is a detailed cross-sectional view of one of the pin cells 60 shown in FIG. 5, in a neutral state;

FIG. 7 is a detailed cross-sectional view of one of the pin cells 60 shown in FIG. 6, in a loaded state;

FIG. 8 is a schematic view of the pin cell shown in FIG. 6;

FIG. 9 is a schematic view of the pin cell shown in FIG. 7;

FIG. 10 is an exploded simplified perspective view of the chuck body shown in FIGS. 4 and 5;

FIG. 11 is a detailed perspective view of a region of the chuck body shown in FIG. 10;

FIG. 12 is a detail perspective view of a region of the base layer shown in FIG. 11;

FIG. 13 is a top-down view of the region shown in FIG. 12;

FIG. 14 is a cross-sectional view of the region shown in FIG. 13, taken along lines 14—14;

FIG. 15 is a detail perspective view of a region of the pin layer shown in FIG. 11;

FIG. 16 is a top-down view of the region shown in FIG. 15; and

FIG. 17 is a cross-sectional view of the region shown in FIG. 16, taken along lines 17—17.

DETAILED DESCRIPTION OF THE INVENTION

FIG. 1 depicts a lithographic system 10 in accordance with one embodiment of the present invention that includes a pair of spaced-apart bridge supports 12 having a bridge 14 and a stage support 16 extending therebetween. Bridge 14 and stage support 16 are spaced-apart. Coupled to bridge 14 is an imprint head 18, which extends from bridge 14 toward stage support 16. Disposed upon stage support 16 to face imprint head 18 is a motion stage 20. Motion stage 20 is configured to move with respect to stage support 16 along X- and Y-axes and may provide movement along the Z-axis as well. A source 22 of energy is coupled to system 10 to generate and impinge actinic energy upon motion stage 20. As shown, source 22 is coupled to bridge 14.

Referring to both FIGS. 1 and 2, connected to imprint head 18 is a template 24 having a patterned mold 26 thereon that may be patterned or substantially smooth, if not planar. An exemplary template 24 is shown in U.S. Pat. No. 6,696,220, which is incorporated by reference herein. In the present example, mold 26 is patterned so as to include a plurality of features defined by a plurality of spaced-apart recesses 28 and projections 30. Projections 30 have a width W_1 , and recesses 28 have a width W_2 , both of which are measured in a direction that extends transversely to the Z-axis. The plurality of features defines an original pattern that forms the basis of a pattern to be transferred into a substrate 32 positioned on motion stage 20. To that end, imprint head 18 is adapted to move along the Z-axis and to vary a distance “d” between patterned mold 26 and substrate 32. Alternatively, or in conjunction with imprint head 18, motion stage 20 may move template 24 along the Z-axis. In this manner, the features on patterned mold 26 may be imprinted into a flowable region of substrate 32, discussed more fully below. Source 22 is located so that patterned mold 26 is positioned between source 22 and substrate 32. As a result, patterned mold 26 is fabricated from material that allows it to be substantially transparent to the energy produced by source 22.

Referring to FIG. 2, substrate 32 is patterned with a formable material that may be selectively solidified. To that end, the polymerizable material, shown as a plurality of spaced-apart discrete droplets 38, are disposed between

mold 26 and substrate 32. Although the polymerizable material is shown as a plurality of droplets 38, the polymerizable material may be deposited employing any known technique, including spin coating techniques or wicking techniques. An exemplary wicking technique is discussed in U.S. Pat. No. 6,719,915, which is incorporated by reference herein. The polymerizable material may be selectively polymerized and cross-linked to record on substrate 32 an inverse of the original pattern therein, defining a recorded pattern, shown as an imprinting layer 34, in FIG. 3. Thereafter, suitable etch processes may be employed to transfer a desired pattern into substrate 32. In this regard, the term substrate is employed in a broad sense as including a bare semiconductor wafer, with or without a native oxide layer present thereon or with pre-existing layers, such as a primer layer formed from a material sold under a tradename DUV30J-6 available from Brewer Science, Inc. of Rolla, Mo.

Referring to FIGS. 2 and 3, the pattern recorded in imprinting layer 34 is produced, in part, by mechanical contact of droplets 38 with both substrate 32 and patterned mold 26. To that end, the distance “d” is reduced to allow droplets 38 to come into mechanical contact with substrate 32, spreading droplets 38 so as to form imprinting layer 34 with a contiguous formation of the imprinting material over surface 36 of substrate 32. In one embodiment, distance “d” is reduced to allow sub-portions 46 of imprinting layer 34 to ingress into and to fill recesses 28.

In the present embodiment, sub-portions 48 of imprinting layer 34 in superimposition with projections 30 remain after the desired, usually minimum distance “d”, has been reached, leaving sub-portions 46 with a thickness t_1 and sub-portions 48 with a thickness t_2 . Thickness t_2 is referred to as a residual thickness. Thicknesses “ t_1 ”, and “ t_2 ” may be any thickness desired, dependent upon the application. The total volume contained in droplets 38 may be such so as to minimize, or to avoid, a quantity of material 40 from extending beyond the region of surface 36 in superimposition with patterned mold 26, while obtaining desired thicknesses t_1 and t_2 .

Referring to FIGS. 2 and 3, after a desired distance “d” has been reached, source 22 produces actinic energy that polymerizes and cross-links the polymerizable material, forming layer 34 with cross-linked polymerized material. Specifically, layer 34 is solidified having a side 36 with a shape conforming to a shape of a surface 50 of patterned mold 26. As a result, imprinting layer 34 is formed having recessions 52 and protrusions 54. After formation of imprinting layer 34, distance “d” is increased so that patterned mold 26 and imprinting layer 34 are spaced-apart. This process may be repeated several times to pattern different regions (not shown) of substrate 32, referred to as a step and repeat process.

Referring to FIGS. 1, 4 and 5, motion stage 20 includes a chucking system 57 upon which to support substrate 32, which includes a body 58 having a plurality of pin cells 60 surrounded by a rim 62. Specifically, body 58 includes a surface 64 surrounded by rim 62. Pin cells 60 include a pin 61 that extends from surface 64. Pin 61 includes a pair of spaced-apart contact surfaces 66 lying in a plane P. An apex surface 68 of rim 62 lies in plane P. Upon resting atop of rim 62, substrate 32 defines a chamber (not shown) between surface 64 and substrate 32, with pins 61 being disposed within the chamber (not shown). A pump (not shown) may be placed in fluid communication with the chamber (not shown) to evacuate the same, holding a periphery of sub-

strate 32 firmly against rim 62 forming a seal. The remaining portion of substrate 32 surrounded by the seal is supported by pins 61.

Referring to FIGS. 4 and 6, one or more of pin cells 60 are designed to minimize contact area with substrate 32. As a result, one or more of pins 61 have a T-shaped cross-section that includes a cross-member 70 having a pair of spaced-apart contact lands 72 extending therefrom and terminating in contact surface 66, defining a recess 74 therebetween. Recess 74 includes a nadir surface 76. A base portion 78 of cross-member 70, disposed opposite to nadir surface 76, is supported by a flexure stem 80. A pair of opposed sides 82 extends from base portion 78, terminating in contact surface 66. Extending from each of side surfaces 82, away from recess 74 is a side flexure 84. Specifically, each of side flexures 84 extends between a side wall 86 and one of side surfaces 82. Each side wall 86 extends from a support region 88, terminating in a surface 90. Surface 90 is spaced-apart from substrate 32 and in the present example lies in a common plane with nadir surface 76. Foundation region 88 extends between opposed side walls 86. Flexure stem 80 extends between foundation region 88 and base portion 78.

Pin cells 60 are configured so that contact lands 72 are equally loaded with force to which the same is subjected by substrate 32 resting on one of pins 61. In this manner, the load to which a given pin cell 60 is subjected is transferred to ground, i.e., foundation region 88. As a result each of pin cells 60 operates much like an ordinary pin-type chuck when supporting a "uniform normal load". However, unlike typical pin-type chucking mechanisms, in the presence of a non-uniform load, e.g., in the presence of a particulate contaminant 92 disposed between substrate 32 and one or more of contact lands 72, one or more of pins 61 becomes compliant. Specifically, flexure stem 80 and side flexures 84 flex, allowing pins 61 to be compliant. This minimizes, if not abrogates, non-planarity in substrate 32 due to the presence of particulate contaminant 92. To that end, it is desired that the height of each of contact lands 72, measured between nadir surface 76 and contact surface 66, has a magnitude no less than the maximum dimension of anticipated particulate contaminants. As a result, in the presence of particulate contaminant 92, shown more clearly in FIG. 7, being disposed between contact surface 66 and substrate 32, cross-member 70 moves so as to avoid generation of non-planarity in substrate 32 due to particulate contaminant.

This is accomplished, in part, by establishing the relative bending stiffness of the various elements of each of pin cells 60 to obtain a desired movement of pin 61. For example, the bending stiffness of flexure stem 80 is less than the bending stiffness of either cross-member 70 or side flexures 84. The bending stiffness of cross-member 70 is substantially greater than side flexures 84. As a result, cross-member 70 is considered a rigid body. By establishing the relative bending stiffness among the components as mentioned above, rotation of cross-member 70 occurs about a remote axis, i.e., an axis spaced-apart from cross-member 70. As shown, various axes 93, 94, 95, 96, 97, 98, 99, 100, 101, 102, 103, 104, 105, 106 and 107 may function as the remote axis and, for a given pin 61, the axis among axes 93, 94, 95, 96, 97, 98, 99, 100, 101, 102, 103, 104, 105, 106 and 107 is dependent upon the size of particulate contaminant 92 and current configuration, i.e., designed bending stiffness ratio of flexure stem 80 to side flexures 84.

Referring to both FIGS. 8 and 9, an important consideration in preventing out-of-plane distortion of substrate 32 upon flexing of pin 61 in the presence of particulate contaminant 92 is to ensure that potential remote axis is properly

positioned. In the present example, the potential remote axis, e.g., one of axes 93, 94, 95, 96, 97, 98, 99, 100, 101, 102, 103, 104, 105, 106 and 107 does not lie between contact lands 72. Rather it is desired that each of the potential remote axis, e.g., axes 93, 94, 95, 96, 97, 98, 99, 100, 101, 102, 103, 104, 105, 106 and 107 lie between contact land 72, without having particulate contaminant 92, and closest to side wall 86. With this configuration the presence of particulate contaminant 92 on one of contact lands 72 will cause pin 61 to move away from substrate 32 without the remaining contact land 72, positioned between particulate contaminant 92 and the remote axis, from extending upwardly toward substrate 32, beyond plane P in the presence of particulate contaminant 92. More specifically, contact land 72 having particulate contaminant 92 thereon is subjected to a greater load than the remaining contact land 72. By providing rotation of pin 61 about an rotational axis spaced apart from land 72 having particulate contaminant 92 thereon as discussed above, out-of-plane distortion of substrate 32 due to compliance of pin cell 60 to the presence of particulate contaminant 92 is avoided.

Referring to FIGS. 1 and 10, body 58 of chuck system 57 may be fabricated from virtually any material, including aluminum, stainless steel, silicon, silicon carbide and the like, or a combination of these materials. In the present example, body 58 is fabricated employing standard semiconductor processes. To that end, body 58 is formed from three distinct layers, shown as foundation layer 110, base layer 112 and pin layer 114. Foundation layer 110 merely comprises a body formed from silicon. Foundation layer 110 has opposing surfaces 116 and 118, one of which, for example surface 116, is substantially smooth, if not planar. A throughway 120 is centrally disposed in foundation layer 110 and extends between opposing surfaces 116 and 118. Throughway 120 may have any suitable diameter. In the present example a diameter of throughway 120 is approximate 3 millimeters. Exemplary dimensions foundation layer 110 are 100 millimeters.

Base layer 112 includes a centrally disposed through hole 121 adapted to be in superimposition with throughway 120 when base layer 112 and foundation layer 110 are placed in a final seating position. In the present example the diameter of through hole 121 is approximately 2 millimeters. Typically, the entire surface of base layer 112 that faces pin layer 114 is covered with base cells 122, excepting the region in which through hole 121 is present and region 119 which is located at a periphery of base layer 112 in superimposition with rim 115 of pin layer 114. However, eight base cells 122 are shown for simplicity. The detailed arrangement of an array of nine base cells 122 is discussed with respect to region 123, shown more clearly in FIG. 11, as well as FIG. 12.

Referring to both FIGS. 11 and 12, each base cell 122 includes flexure stem 80, motion relief regions, shown as voids 125, in which flexure stems 80 are disposed, and recessed regions 124 and 126, as well as vacuum channels 128 extending in pairs from each of voids 125, with adjacent pairs of vacuum channels 128 extending orthogonally to one another.

Stem 80 is fabricated to facilitate flexing along direction 132. To that end, disposed on opposed sides of flexure stem 80 are recessed regions 126, with each of recessed regions being flanked by a pair of vacuum channels 128, extending along direction 132. Specifically, regions 126 are disposed on opposing sides of flexure stem 80 with each region 126 extending from void 125 away from flexure stem 80. Recess regions 124 are arranged in two pairs, with each of the two

pairs of regions **124** being disposed on opposing side of flexure stem **80**. Each of recessed regions **124** associated with each pair extends from one of the vacuum channels **128**, extending adjacent to one of recessed regions **126**, away from the remaining recessed regions **124** associated with the pair.

In an exemplary embodiment, a width **140** of flexure stem **80** measured along direction **132** is approximately 0.05 millimeter. A length **141** of flexure stem **80**, measured along direction **134** is approximately 0.3 millimeter, with flexure stem **80** extending from foundation support **88**, along direction **136** a distance **142** of approximately 0.35 millimeter. A width **143** of each vacuum channel, measured transversely to a height thereof that is determined along direction **136**, is approximately 0.1 millimeter. Regions **124** and **126** are recessed a distance sufficient to allow pin **61** to flex in response to a particle contaminant no greater than the largest sized particulate contaminant anticipated and to ensure that the structural integrity of pin **61** is not compromised when subjected to forces produced by the presence of a larger particulate contaminant. In the present example, regions **124** and **126** are recessed a distance of approximately 0.01 millimeter with respect to an apex **153** of flexure stem **80**, along direction **136**. A width **145** of pin cell **60** measured along direction **132** is approximately two millimeters, and a length **146** of pin cell **60** measured along direction **134** is approximately two millimeters. A distance **147** between adjacent vacuum channels **128** of a given pair extending parallel to one another is approximately 0.3 millimeter. A width **148** of regions **126** extending from void **125** along direction **132** is approximately 0.35 millimeter, with regions **126** extending to be coextensive with length **141** of flexure stem **80**. A length **149** of regions **124** extending from an adjacent vacuum channel **128**, along direction **134**, is approximately 0.3 millimeter, with a width **150** measured along direction **132** being approximately 0.5 millimeter. Each of regions **124** are spaced apart from an adjacent vacuum channel **128** extending along direction **134** a distance **151** of approximately 0.1 millimeter. Thickness **152** of base layer **112** is approximately 0.5 millimeter.

Referring to FIG. **10**, pin layer **114** is coextensive with base layer **112**. Typically, the entire surface of pin layer **114** is covered with pin cells **60**, excepting a periphery region thereof in which a raised portion defining a land **115** is positioned surrounding pin cells **60**. However, nine pin cells **60** are shown for simplicity. Pin layer **114** is adapted to be integrally bonded to base layer **112**. For example, region **119** of base layer **112** is coextensive with land **115**. Region **119** is typically bonded to a region of bottom surface **156** in superimposition with land **115** employing silicon fusion techniques. The detailed arrangement of an array of nine pin cells **60** is discussed with respect to region **154**, shown more clearly in FIG. **11**, as well as FIG. **15**.

Referring to both FIGS. **11** and **15**, each of pin cells **60** includes cross-member **70**, having a longitudinal axis **71** extending along direction **132**, with contact lands **72** disposed on opposing ends thereof. In addition, each pin cell **60** includes side wall flexures **84** disposed proximate to one of contact lands **72**. Cross-member **70**, contact lands **72** and flexures **84** are integrally formed with a portion of pin layer **114** in which pin cell **60** is present by forming a plurality of throughways extending between opposed surfaces **155** and **156**. Specifically, formed at each of contact lands **72** is a first pair of u-shaped throughways **157**, having a base portion **158** disposed proximate to contact land **72** and extending along direction **134** a greater extent than contact land **72**,

terminating in a serif portion **159** located at each end of base portion **158**. Serif portions **159** extend from base portion **158** away from contact lands **72**.

A second pair of U-shaped throughways **160** includes a base portion **161** positioned proximate to cross-member **70** and extending between both contact lands **72**. Specifically, base portion **161** extends along direction **132**, transversely to direction **134**, with each end thereof having a first serif portion **162** extending therefrom, away from cross-member **70** parallel to direction **134** and terminating in a second serif portion **163**, defining a pair of second serif portions. Each of second serif portions **163** extends spaced-apart from and parallel to serif **159**. In this manner, defined between each U-shaped throughway **157** and U-shaped throughway **160** is flexure member **84** configured with an L-shaped body. One end of flexure member **84** is connected to a corner of cross-member **70** proximate to a contact land **72**, defining a primary joint **164**. The remaining portion of flexure member **84** extends from primary flexure **164**, terminating in a second end. Disposed proximate to, and spaced-apart from the second end of each flexure member **84** is a rectangular throughway **165**, defining pair of spaced-apart secondary joints **166** proximate to the second end. The portion of flexure member **84** extending between primary joint **164** and secondary joints **166** defines a rigid body **167**.

Referring to FIGS. **15**, **16** and **17**, in an exemplary embodiment, a length **170** of cross-member **70**, measured along direction **132**, is approximately 1 millimeter, and a width **171** of the same, along direction **134**, is approximately 0.3 millimeter. A width **172** of primary joint **164**, measured along direction **132**, is approximately 0.05 millimeter and a length **173** of the same, measured along direction **134**, is approximately 0.1 millimeter. A width **174** of secondary joints **166**, measured along direction **132**, is approximately 0.05 millimeter, and a length **175** of the same, measured along direction **134**, is approximately 0.1 millimeter. A width **176** of rigid body **167**, measured along direction **132**, is approximately 0.3 millimeter, and a length **177** of the same, measured along direction **134**, is approximately 0.2 millimeter. A width **178** and length **179** of contact surface **66** is approximately 0.2 millimeter, measured along directions **132** and **134**, respectively. A height **180** of contact surface **66**, from nadir surface **76** is approximately 0.05 millimeter, measured along direction **136**. A length **181** of base portion **161**, measured along direction **134**, is approximately 0.1 millimeter. A width **183** and length **184** of pin cell **60** is approximately 2 millimeters, measured along directions **132** and **134**, respectively.

Chuck body **58** may be fabricated using any known method. In the present example, chuck body **58** is fabricated from silicon wafers using standard micro-fabrication techniques. As a result, exemplary materials from which chuck body **58** may be fabricated include silicon and/or fused silica. Furthermore, to improve wear resistance, selective surfaces, e.g. contact lands **72**, may be coated with hardened materials, such as silicon nitride, silicon carbide and the like. Typically, base layer **112** is fabricated separately from pin layer **114** and subsequently made integral employing standard techniques, such as, silicon welding, forming device layer **200**. As a result, vacuum channels **128** and void **125** are in fluid communication with throughways **160**, **157** and **166** and throughway **120**. In an exemplary technique, assembly of device layer **200** with foundation layer **110** was undertaken with surface **155** facing an optical flat and a vacuum/electrostatic force being applied to chuck device layer **200**. In this fashion, non-planarity in device layer **200** may be attenuated, if not abrogated. An adhesive is then

applied to either surface of base layer **112** facing foundation layer **110** or surface **116** or both. Device layer **200** is then adhered to foundation layer **110**. It is desired to provide a sufficient volume of adhesive so that non-planarity induced in device layer **200** due to non-planarity in surface **116** is attenuated.

To provide desired lateral stiffness to substrate **32**, adjacent pin cells **60** of chuck body **58** are arranged so that longitudinal axes **71** of cross members **70** of adjacent pin cells **60** extend along orthogonal directions, i.e., neighboring pin cells **60** are oriented at 90 degrees with respect to each other.

The embodiments of the present invention described above are exemplary. Many changes and modifications may be made to the disclosure recited above while remaining within the scope of the invention. For example, foundation layer **110** may be abrogated and device layer may be employed with standard electrostatic and/or vacuum chucking devices. In this fashion, existing chucking systems may be retrofitted with device layer **200** substantially improving the operational characteristics of existing chucking systems. The scope of the invention should, therefore, be determined not with reference to the above description, but instead should be determined with reference to the appended claims along with their full scope of equivalents.

What is claimed is:

1. A substrate support system, comprising:
 - a chuck body having a body surface with a pin extending therefrom having a contact surface lying in a plane, said pin being movably coupled to said chuck body to move with respect to said plane, wherein said pin is coupled to said chuck body to rotate about a remote center of compliance.
 2. The system as recited in claim 1 wherein said pin is coupled to said chuck body to move away from said plane in response to loads being un-evenly distributed on said pin.
 3. The system as recited in claim 2, wherein as a result of said pin moving away from said plane in response to an irregularity on a surface of said substrate, said surface of said substrate remains common to a plane common to a plurality of pairs of spaced-apart contact lands provided by a plurality of pin-cells.
 4. The system as recited in claim 1 wherein said pin is coupled to said chuck body to rotate about a remote center of compliance spaced-apart from a region of said pin having a load thereon that is greater than a load to which the remaining regions of said pin are subjected.
 5. The system as recited in claim 1 wherein said pin is coupled to said chuck body to rotate about a remote center of compliance spaced-apart from a region of said pin having a load thereon that is greater than a load to which the remaining regions of said pin are subjected, while avoiding any of the regions of said pin, lying in said plane, from moving toward said plane.
 6. The system as recited in claim 1 further including a plurality of pins, with said plurality of pins surround by a rim.
 7. The system as recited in claim 1 further including a plurality of pin-cells, each of which further comprises a pin including a cross-member having a longitudinal axis, with the longitudinal axis of cross-members of adjacent pins extending transversely.
 8. The system as recited in claim 1 further including a plurality of pins-cells, each of which further comprises a pin

including a cross-member having a longitudinal axis, with the longitudinal axis of cross-members of adjacent pins extending orthogonally.

9. The system as recited in claim 1 further including a plurality of pins-cells, each of which further comprises a pin including a cross-member having a longitudinal axis, with the longitudinal axis of cross-members of adjacent pins oriented randomly.

10. The system as recited in claim 1 wherein said chuck body is operable for disposing a substrate using an electrostatic force or using a force provided by a vacuum.

11. The system as recited in claim 1 wherein said chuck body comprises a plurality of pin-cells and wherein said plurality of pin-cells are formed by fusing a base layer and a pin layer.

12. A substrate support system, comprising:

a chuck body having a body surface with a pin extending therefrom having a contact surface lying in a plane, said pin being movably coupled to said chuck body to move with respect to said plane, wherein said pin includes a cross-member having two spaced-apart contact lands extending from said cross-member and wherein said pin is formed by a pin cell that further comprises a flexure system coupled between said cross-member and said chuck body.

13. A substrate support system, comprising:

a chuck body having a surface with a "T" shaped pin extending therefrom, said "T" shaped pin including a cross-member having two spaced-apart contact lands extending from said cross-member and wherein said "T" shaped pin is formed by a pin-cell that further comprises a flexure system coupled between said cross-member and said chuck body.

14. The system as recited in claim 13 wherein said "T" shaped pin is coupled to move with respect to said surface.

15. The system as recited in claim 14, wherein as a result of said "T" shaped pin moving with respect to said surface in response to an irregularity on a surface of a substrate, said surface of said substrate remains common to a plane common to a plurality of pairs of spaced-apart contact lands provided by a plurality of pin-cells.

16. The system as recited in claim 13 wherein said "T" shaped pin is coupled to said chuck body to move away from a predetermined position in response to loads being un-evenly distributed thereon.

17. The system as recited in claim 13 further including a plurality of pins, with said plurality of pins surround by a rim.

18. The system as recited in claim 17 further including a plurality of pin-cells, each of which further comprises a pin including a cross-member having a longitudinal axis, with the longitudinal axis of cross-members of adjacent pins extending transversely.

19. The system as recited in claim 17 further including a plurality of pin-cells, each of which further comprises a pin including a cross-member having a longitudinal axis, with the longitudinal axis of cross-members of adjacent pins extending orthogonally.

20. The system as recited in claim 17 further including a plurality of pin-cells, each of which further comprises a pin including a cross-member having a longitudinal axis, with the longitudinal axis of cross-members of adjacent pins oriented randomly.

21. The system as recited in claim 13 wherein said "T" shaped pin is coupled to said chuck body to rotate about a remote center of compliance spaced-apart from a region of

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said pin having a load thereon that is greater than a load to which the remaining regions of said pin are subjected.

22. The system as recited in claim 13 wherein said "T" shaped pin is coupled to said chuck body to rotate about a remote center of compliance spaced-apart from a region of said pin having a load thereon that is greater than a load to which the remaining regions of said pin are subjected, while avoiding any of the regions of said pin, lying in said plane, from moving toward said plane.

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23. The system as recited in claim 13 wherein said chuck body is operable for disposing a substrate using an electrostatic force or using a vacuum.

24. The system as recited in claim 13 wherein said chuck body comprises a plurality of pin-cells and wherein said plurality of pin-cells are formed by fusing a base layer and a pin layer.

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